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Image Analysis in Brain Tumor Detection and Identification Using K-Means Clustering Technique

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Abstract

Brain tumor is a strange boom due to cells reproducing themselves in an uncontrolled way. Magnetic Resonance Image (MRI) is the commonly used device for prognosis. In MR image, the quantity of information is too much for guide interpretation and evaluation. During the beyond few years, mind tumor segmentation in Magnetic Resonance Imaging (MRI) has turn out to be emergent research vicinity within the discipline of scientific imaging machine. Correct detection of length and place of mind tumor performs a essential position in the prognosis of tumor. Image processing is an energetic research location in which medical image processing is a extraordinarily hard discipline. Image segmentation plays a significant position in photograph processing because it facilitates inside the extraction of suspicious regions from the clinical photographs. In this paper an efficient algorithm is proposed for tumor detection based totally on segmentation of mind MRI photographs using k-means clustering.

Keywords: Image Segmentation, K-Means clustering, MRI, Tumor Detection

INTRODUCTION

Image process is a method wherever input image is processed to induce output additionally as a picture or attributes of the image. Main aim of all image process techniques is to acknowledge the image or object into account easier visually. Segmentation of pictures holds an important position within the field of image process. In medical imaging, segmentation is very important for feature extraction, image measurements and image show. A neoplasm is outlined as a mass that grows with none management of traditional forces. Real time designation of tumors by exploitation additional reliable algorithms has been a lively of the most recent developments in medical imaging and detection of tumor in mister and CT scan pictures. Therefore image segmentation is that the basic downside utilized in neoplasm detection. Image segmentation is outlined because the partition or segmentation of a digital image into similar regions with a main aim to change the image into account into one thing that's additional substantive and easier to investigate visually. Image segmentation strategies is classified as thresholding, region primarily based, supervised and unsupervised techniques.

MRI is commonly used in the clinical field for detection and visualization of details inside the inner shape of the frame. It is used to come across the differences in the frame tissues that's significantly better technique compared to computed tomography(ct). For that reason this approach turns out to be a unique technique specially for the brain tumor detection and cancer imaging. Protons and neutrons of an atom have an angular momentum that's known as a spin. Those spins will cancel when the wide variety of subatomic particles in a nucleus is even and nuclei with a typical wide variety may have a resultant spin. This forms the premise of magnetic resonance imaging. a magnetic resonance imaging (MRI) scanner makes use of powerful magnets to polarize and excite hydrogen nuclei (single proton) in human tissue, which produces a sign that can be detected and it is encoded spatially, ensuing in photographs of the body.

Clustering is a crucial tool for a range of applications. Bunch is division of information into teams of comparable objects. Every cluster consists of objects that square measure similar between themselves and dissimilar to things of different teams. From the machine learning perspective, bunch may be viewed as unattended learning ideas. Unattended machine learning implies that bunch doesn't rely differing kinds of clusters reckoning on the predefined categories and coaching examples whereas classifying the information objects. Bunch algorithms square measure principally divided into 2 techniques: stratified algorithms and partition algorithms. A stratified bunch algorithmic rule divides the given information set into smaller subsets in fashion. A partition bunch algorithmic rule partitions the information set into desired range of sets in an exceedingly single step. various strategies are planned to resolve bunch drawback, the foremost fashionable bunch methodology is K-Means bunch algorithmic rule. This algorithmic rule is a lot of outstanding to cluster

huge information quickly and expeditiously. thus it may be employed in image process techniques particularly in segmentation.

All through the acquisition of clinical images, there are opportunities that the clinical photo is probably degraded due to issues that may arise throughout the acquisition degree. So the unique photo might not be appropriate for analysis. Noise provided within the photo can decrease the potential of segmentation set of rules. so it is vital to clear out any noise inside the primitive photograph before segmentation. There may be a extensive variety of filters available to get rid of the noise from the pictures. Common filters for instance, can dispose of that noise but with the sacrifice of sharpness of picture. Median clear out is an instance of common clear out used to take away the noise like salt and pepper. Polishing is commonly carried out through the usage of excessive bypass filters. Gaussian filter out (an excessive pass filter) is used to enhance the boundaries of the item. This is crucial as edges will detect and highlight the tumor for us.

The remaining a part of the paper is prepared as follows: phase ii includes the works associated with in all likelihood solutions for brain tumor detection and segmentation. Phase iii entails the description of the proposed technique. Segment iv involves the simulation outcomes of the proposed paintings. The paper is concluded in section v.

RELATED WORK

This section offers with the works associated with the mind tumor detection and segmentation in scientific photos. Somkantha, et al [1] designed a brand new facet following technique for boundary detection in noisy photographs and applied it to object segmentation problem in scientific image. The proposed approach was implemented to discover the object barriers in numerous styles of noisy pix in which the ill-defined edges had been encountered. Gooya, et al [2] supplied a way glister for segmentation of gliomas in multi-modal MR photographs by way of joint registering the snap shots to a probabilistic atlas of wholesome individuals. The predominant contribution of the paper was the incorporation of tumor increase model to undertake the normal atlas into the anatomy of the patient brain. Parisot, et al [3] pondered a one of a kind method for detection, segmentation and characterization of brain tumors. This method exploits earlier information in the form of a sparse graph delineating the expected spatial positions of tumor instructions. In this paper, implied a unique manner to encode earlier expertise in tumor segmentation, making use of the fact that the tumors have a tendency to appear in the brain in preferential places. They mixed a photograph based totally detection scheme with identity of the tumor's corresponding preferential vicinity, which became associated with a selected spatial behavior. Manikis, et al [4] cautioned a novel framework for assessing tumor modifications based totally on histogram evaluation of temporal magnetic resonance image (MRI) facts. The proposed technique detects the distribution of tumor and quantitative fashions its increase or shrinkage imparting the potential to assist clinicians in objectively assessing subtle changes for the duration of therapy. Bauer, et al [5]

determined a singular technique to adapt a healthy mind atlas to MR pictures of tumor patients. They offered a brand new method which uses state-of-the-art fashions of bio-physio mechanical tumor boom to evolve a fashionable brain atlas to an individual tumor patient image.

Roy, et al [6] counseled an analysis on automatic mind tumor detection and segmentation from MRI of brain. brain tumor segmentation changed into a full-size manner to extract data from complex MRI of brain images. Sindhushree. ok.s, et al [7] have developed a mind tumor segmentation method and proven segmentation on dimensional MRI facts. Also, detected tumors are represented in 3 dimensional view. Excessive skip filtering, histogram equalization, thresholding, morphological operations and segmentation using connected element labeling changed into carried out to hit upon tumor. Two dimensional extracted tumor photos were reconstructed into 3 dimensional volumetric data and the volume of the tumor become also calculated. M.C. Join Christ and R.M.S. Parvathi [8] proposed a method that integrates ok-way clustering with marker managed watershed segmentation algorithm and integrates fuzzy c manner clustering with marker controlled watershed segmentation algorithm did one by one medical photo segmentation. P.Vasuda and S.Satheesh [9] proposed a method to locate tumors from MRI snap shots the usage of fuzzy clustering technique. This set of rules makes use of fuzzy c-manner but the principal disadvantage of this algorithm is the computational time required. Logeswari and Karan [10] studied the performance of the MRI image in terms of weight vector, execution time and tumor pixels detection. A tumor was a mass of tissue that grows out of control of the normal forces that regulates growth. The convoluted brain tumors were scattered into two broad classes depending on the tumor's origin, their growth pattern and malignancy.

Roy and Bandyopadhyay [11] proposed an interactive segmentation method that enables users to quickly and efficiently segment tumors in MRI of brain. They implied a new method that in addition to area of the region and edge information uses a type of prior information also its symmetry analysis, which was more consistent with pathological cases. Xavier Arockia Raj, et al [12] proposed a paper for brain tumor detection using converted histogram thresholding-quadrant approach. In medical image processing, brain tumor detection was one of the challenging task, since brain images were complicated and tumors were analyzed only be expert physicians. M.K.Kowar and Yadav [13] presented a novel technique for the detection of tumor in brain using segmentation and histogram thresholding. In this paper, a technique to detect presence of the brain based on thresholding technique has been developed. A.Mustaqeem, et al [14] implemented an efficient brain tumor detection releases level sets for 3D tumor segmentation (TLS). In this scheme the level set speed function was designed using a global threshold. This threshold was defined based on the idea of confidence intervals and iteratively updates throughout the evolution process.

PROPOSED METHOD

The segmentation of the brain MRI images for detection of tumors using K-Means clustering technique. A cluster can be defined as a group of pixels where all the pixels in certain group defined by similar relationship. Clustering is also unsupervised classification because the algorithm automatically classifies objects based on user given criteria. Here K-Means clustering algorithm for segmentation of the image is used for tumor detection from the brain MRI images. The proposed block diagram is as shown.



Fig.1 Proposed Block Diagram

MRI scans of the human brain forms the input images for our system where the grayscale MRI input images are given as the input. The preprocessing stage will convert the RGB input image to grayscale. Noise present if any, will be removed using a median filter. The image is sharpened using Gaussian filtering mask. The preprocessed image is given for image segmentation using K-Means clustering algorithm.

1 Image Acquisition

Image are received the usage of MRI scan and these scanned photos are displayed in a dimensional matrices having pixels as its factors. Those matrices are dependent on matrix length and its field of view. Photos are saved in photograph report and displayed as a grayscale picture. The entries of a grayscale image are starting from 0 to 255, in which zero indicates general black coloration and 255 shows pure white coloration. Entries between those stages vary in intensity from black to white.

2 Pre-processing stage

In this phase image is enhanced in the way that finer details are improved and noise is removed from the image. Most commonly used enhancement and noise reduction techniques are implemented that can give best possible results. Enhancement will result in more prominent edges and a sharpened image is obtained, noise will be reduced thus reducing the blurring effect from the image. In addition to enhancement, image segmentation will also be applied. This improved and enhanced image will help in detecting edges and improving the quality of the overall image. Edge detection will lead to finding the exact location of tumor.

2.1 Noise Removal

Many filters are used to remove the noise from the images. Linear filters can also serve the purpose like Gaussian, averaging filters. For example average filters are used to remove salt and pepper noise from the image. Because in this filter pixel's value is replaced with its neighborhood values. Median filter is also used to remove the noise like salt and pepper and weighted average filter is the variation of this filter and can be implemented easily and give good results. In the median filter value of pixel is determined by the median of the neighboring pixels. This filter is less sensitive than the outliers.

2.2 Image Sharpening

Sharpening of the image can be achieved by using different high pass filters. As now noise is being removed by using different low pass filters, we need to sharpen the image as we need the sharp edges because this will help us to detect the boundary of the tumor. Gaussian high pass filter gives very high rated results and used very widely to enhance the finer details of the project.

3 Segmentation using K-Means clustering

Segmentation is an essential process to extract information from complex medical images. The main objective of the image segmentation is to segregate an image into commonly exclusive and exhausted regions such that each region of interest is spatially contiguous and the pixels within the region are homogeneous with respect to a predefined criterion.

- 1. Let D be the data points in the given input image
- 2. Partition the data points into k equal sets
- 3. In each set, take the middle point as the initial centroid
- 4. Compute the distance between each data point $(1 \le i \le n)$ to all initial centroids $(1 \le j \le k)$
- 5. For each data point *di*, find the closest centroid *cj* and assign *di* to cluster j
- 6. Set *clu*[*i*]=*j*
- 7. Set *Neare*[*i*]=*d*(*di*,*cj*)

- 8. For each cluster $(1 \le j \le k)$, recalculate the centroids
- 9. For each data point *di*,
- (i) Compute its distance from the centroid of the present nearest cluster

(ii) If this distance is less than or equal to the present nearest distance, the data point stays in the same cluster. Otherwise compute the distance (di) for every centroid $(1 \le j \le k)$

10. Repeat from steps 5 to 9 until convergence is met

Fig.2 Steps for the proposed algorithm

RESULTS

Some of the brain MR images containing tumor taken for testing our proposed algorithm are shown in Fig 3.



Fig.3 Brain MR images containing tumor

The brain tumor location is found out by applying our proposed algorithm. Fig 4 shows the final clustering of brain MR image after being processed by our algorithm. Fig 5 shows the final tumor detected portion from the brain MR image.



Fig.4 Clustering of brain MR image



Fig.5 Tumor detected

CONCLUSION

Segmentation of brain image is imperative in surgical planning and treatment in the field of medicine. In this work, we have proposed a computer aided system for brain MR image segmentation for detection of tumor location using K-Means clustering algorithm. The proposed brain tumor detection comprises three steps: image acquisition, pre-processing, and K-Means clustering. We were able to segment tumor from different brain MR images from our database.

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